

Amendments to the Specification

Please replace the title as follows:

ELECTRIC-COMPONENT MOUNTING SYSTEM

Please replace paragraph [0137] with the following rewritten paragraph:

[0137] Then, the control flow goes to step S2 to operate the first image-taking device 52 to take an image of the thermal-expansion detecting mark 54. Step S3 is then implemented to calculate distances of deviation of the position of the image of the detecting mark 54 with respect to its nominal position in the X-axis direction and the Y-axis direction, as the robot-position thermal-expansion amounts ΔX_{EP} and ΔY_{EP} in the respective X-axis and Y-axis directions.

Please replace the Abstract with the attached substitute Abstract.